



# Land Navigation







# **Course Objectives**

At the conclusion of this course the student should understand the following:

- •Compass and Map Basics
- Traveling to a Target
- •Topo Map Basics
- Distance Calculations
- Finding Yourself
- •UTM / USNG Coordinate System
- •Using GPS with a Map
- Declination





# P.A.C.E.

System for Search and Rescue

- **P**RIMARY GPS, Phone Apps
- ALTERNATE Map and Compass
- CONTINGENCY Terrain Association
- EMERGENCY PLBs

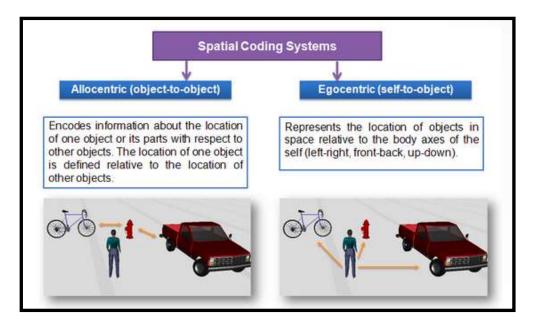




# **Spatial Navigation Methods**

**Egocentric:** locating objects in a space in reference to yourself (left, right, front, back, etc.).

**Allocentric:** locating objects in space with respect to other objects.







# **Compass Types**

Mirrored – Sighting

(Preferred)



Baseplate



Digital



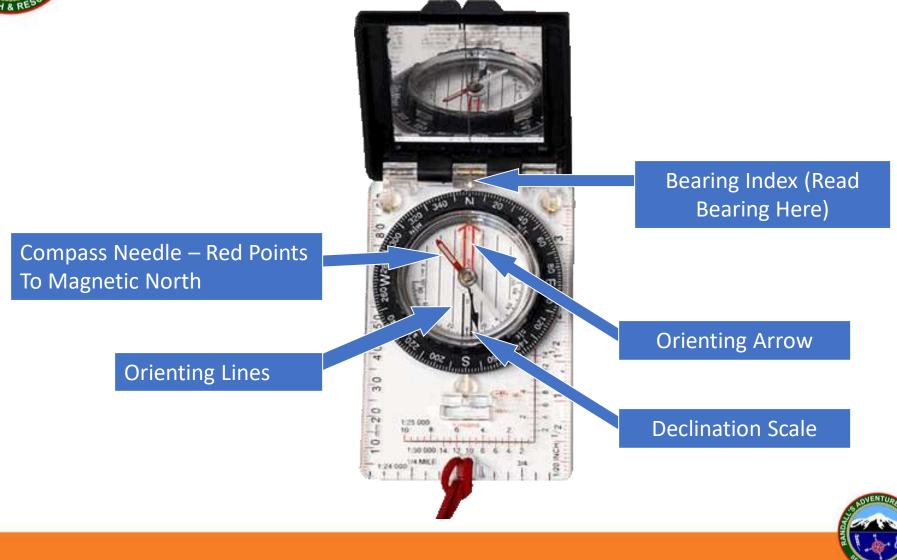
Accessory



Lensatic





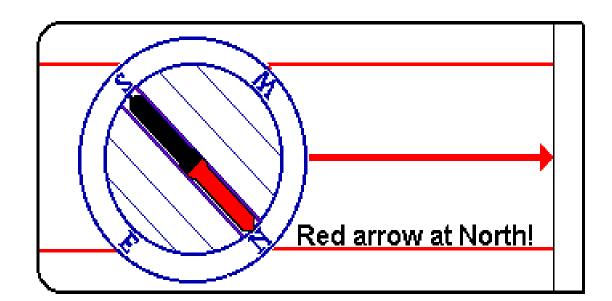






# **Boxing a Compass**









index line.

reference line.

#### **RAT-SAR**



#### **Map Orientation**

With Compass Adjusted For Declination

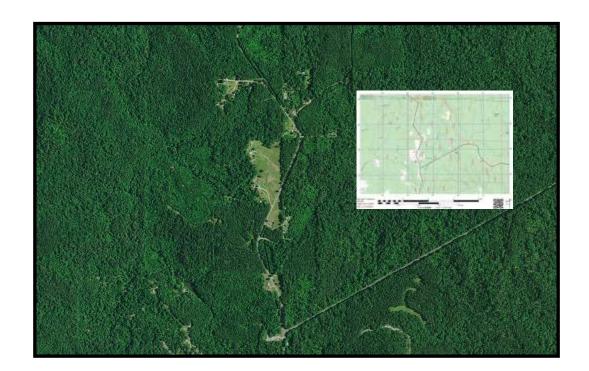
- 1) Adjust "N" to index line.
- Align edge of baseplate 2) with map meridian.
- Box compass needle by 3) rotating map.





#### **Map Orientation**

**Using Terrain Features** 

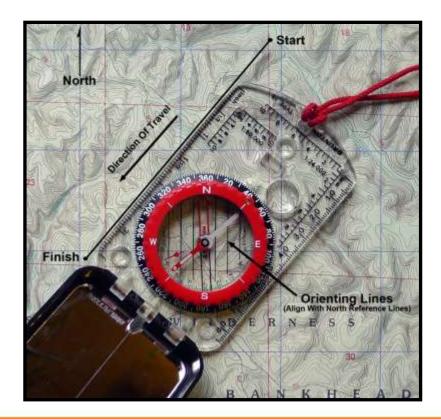






# Finding an Azimuth Using a Compass

Preferred method for accuracy. Map must have grid lines.



- Draw a line from start to finish.
- Lay the edge of your compass on the line *in the direction you are traveling*.
- Rotate the compass bezel until the orienting lines align with your North Reference Lines (*Make sure that North is pointing to North on the map*).
- Pick up your compass, box the needle, and travel to the destination.
- Note: The compass shown has already been adjusted for declination.







# Finding an Azimuth Using a Protractor

**Using Grid Lines** 

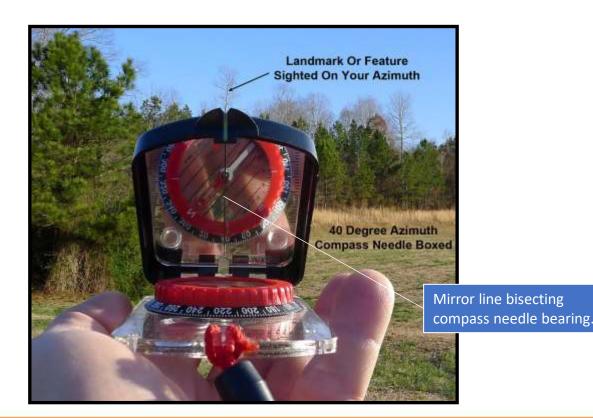


- Draw a line from start to finish.
- Lay the compass rose or protractor on the line so the line crosses through the center of the rose.
- Align N / S line or orienting lines on the compass rose with Reference Line.
- Read your azimuth on the "Finish" side of the compass rose.
- Note: you will have to add or subtract the declination value to the value.





#### Traveling to a Target



- Use the mirror properly.
- Hold the compass at eye level.
- Use the mirror line to ensure the compass is aligned properly.
- Use the sighting notches to find a distant target.
- After a target is acquired, put the compass down and walk to your target. Do not try to walk while watching your compass.





# Posting Up



In addition to using natural landmarks as targets for your direction of travel, you can also post up a member of your team as a target.

Posting up is handy for working around thick areas or navigation at night.

Another option is the Back Azimuth.







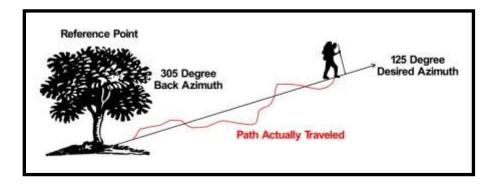
#### **Back Azimuth**

Use a Back Azimuth if you need to verify you are still on your desired direction of travel. This is especially handy when crossing rivers or boxing around objects.

Back Azimuth is 180 degrees from your target azimuth. If your target azimuth is more than 180 degrees, then subtract 180. If it is less than 180, then add 180.

#### Class Question:

If you travel 100 meters on a bearing of 40 degrees and then on a bearing of 60 degrees for 300 meters, can you get back to your starting point without a map? What route would you take?







#### **Boxing Around an Object**

Example: direction of original travel is 45 degrees.

- Turn 90 degrees to a new azimuth of 135 (count your paces).
- Turn 90 degrees back to the original azimuth of 45 degrees until you are past obstacle.
- Turn 90 degrees to a new azimuth of 315 and pace the same amount as the first turn.
- Turn 90 degrees back to the original azimuth of 45 degrees and continue on.











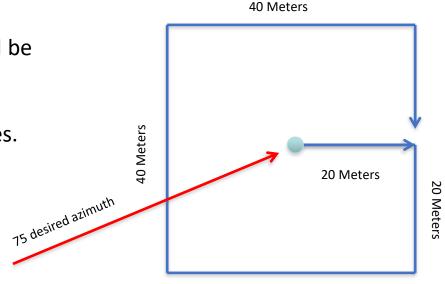
#### Lateral Drift

If you cannot find your target after walking your azimuth the correct distance, then mark the spot where you think it should be and began a structured search of the area.

Make note of your azimuths, pace count, and direction changes.

Start your grid small then go larger if you cannot locate the target.

Alternate Method: Skirmish line as you approach.



40 Meters



#### **Gross Direction Navigation**

As obvious from this simple road map, the lost hiker only needs to travel a westerly direction to cross a road and reach civilization.

Always know which general direction crosses a main artery!

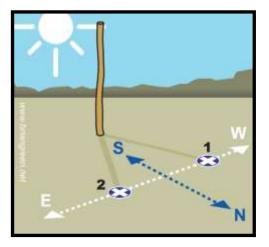
When using a map and compass always have a "panic azimuth."



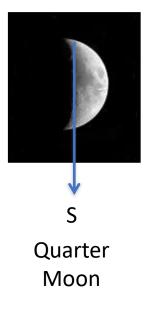


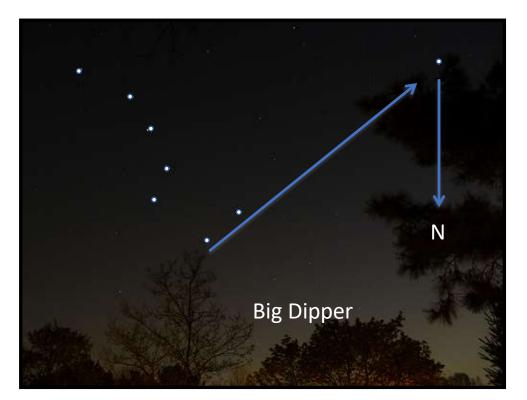


#### **Gross Direction Navigation Aids**



Shadow Stick









#### **Terrain Association Navigation**

- The most widely used method of navigation.
- The navigator plans his route so that he moves from terrain feature to terrain feature.
- An automobile driver in a city uses this technique as he moves along a street or series of streets, guiding on intersections or features such as stores, parks or houses.
- Like the driver, the navigator selects routes or streets between key points or intersections. These key points can be lakes, mountains, roads or any other terrain feature readily recognized on a map.
- Before you hike a new area, familiarize yourself with the terrain by studying maps, satellite photos or other available information.





#### Backstops, Handrails & Aiming Off

BACKSTOPS are features that typically run perpendicular to your azimuth and located beyond your target point. If you run into your backstop then you know you have traveled too far and missed your target point. Backstops can be rivers, roads, mountains, railroad tracks or other useable features.

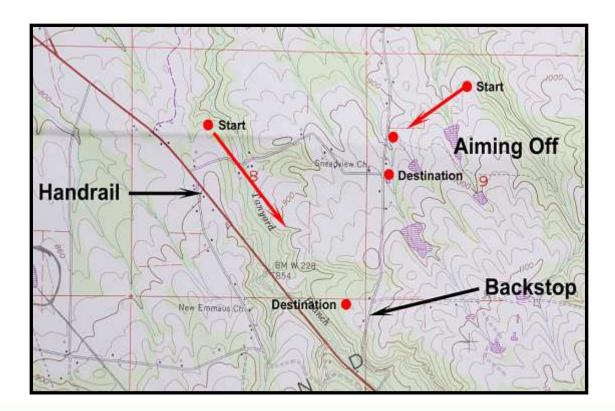
HANDRAILS are features that run parallel to your azimuth. They can be rivers, roads, mountains, or other useable features that the navigator can use to continue traveling in the desired direction.

AIMING OFF is a process of deliberately adding or subtracting to the desired azimuth so the navigator knows which way to go once they reach a feature (such as a trail or road) that leads to the target.





#### Backstops, Handrails & Aiming Off

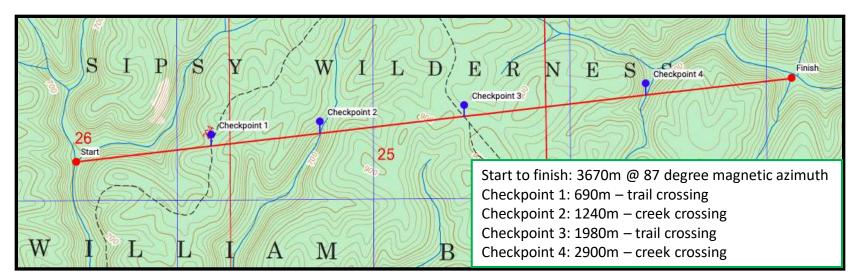






#### Checkpoints

Checkpoints are features on the map that will be readily noticeable when navigating in the field, thus allowing you to verify your course and distance traveled. Checkpoints are established and noted before beginning field navigation.



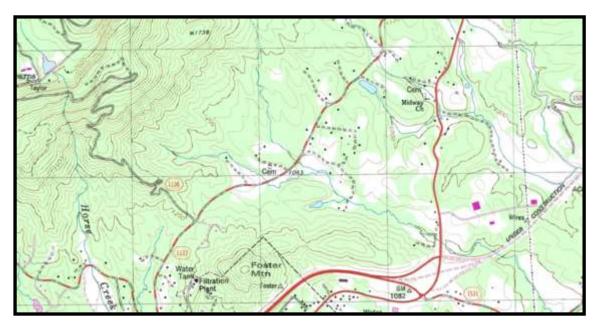






#### **Topo Maps**

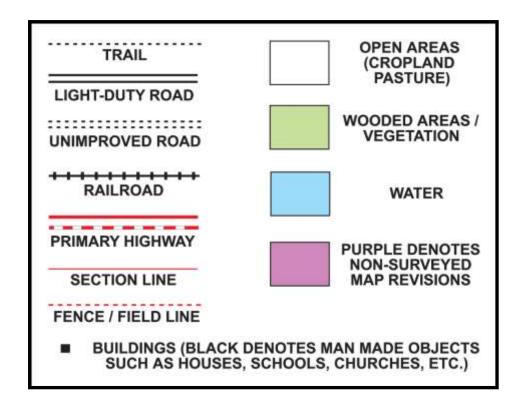
Topographic Maps are maps which portray the shape and elevation of the terrain while showing a graphic representation of selected man-made and natural features.







#### **Basic Symbols / Legends**



The Map Legend is a side table or box on a map that shows the meaning of the symbols, shapes, and colors used on the map.

Most maps will also have a scale, declination value, UTM zone, the datum the map is printed in, and revision dates.

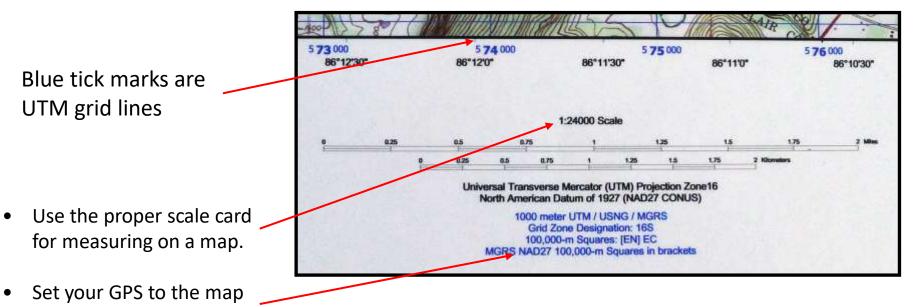






datum shown on your map.

#### Map Scale & Datum

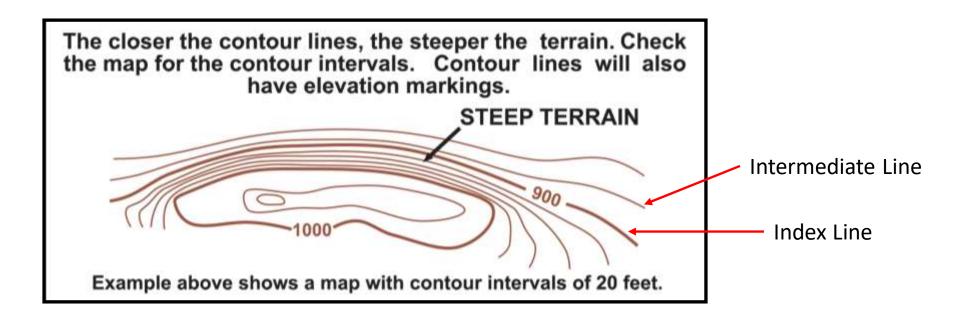


A 7.5 minute quadrangle topo map is scaled at 1:24,000. 1:24,000 scale means 1" on the map equals 24,000 inches in real terrain.





#### **Contour Lines**

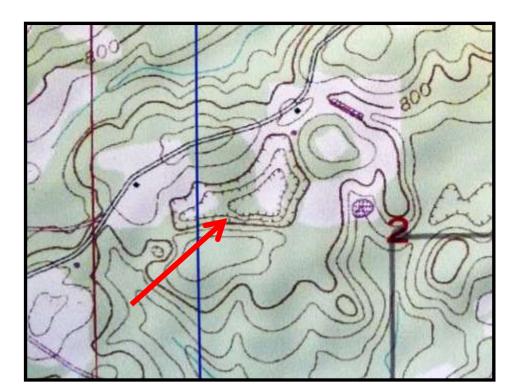








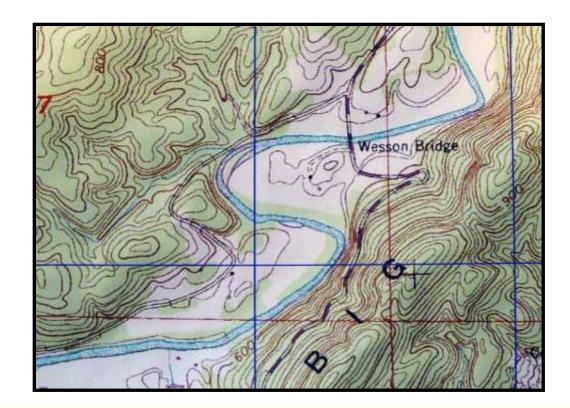
#### Depression







#### **Continuous Water Flow**







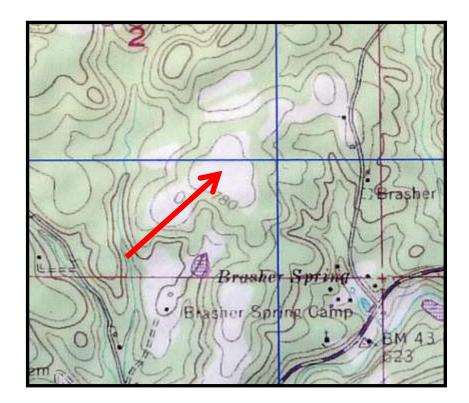
#### **Intermittent Water Flow**







#### **Clear Areas / Fields**

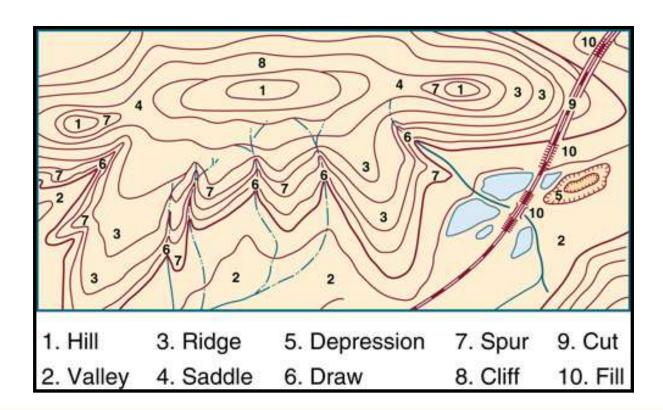


Wooded and clear areas may not be accurately represented depending on the last map revision.





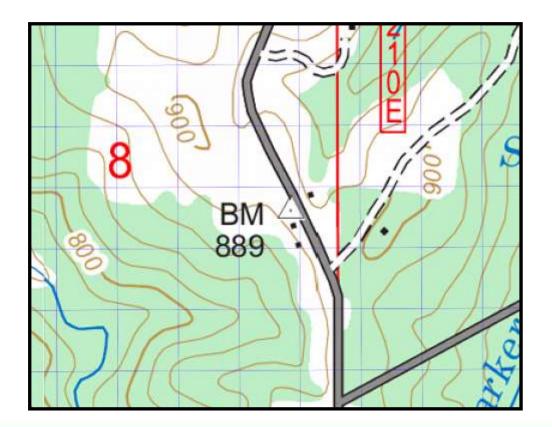
#### **NASAR Graphic**







#### **Benchmarks**

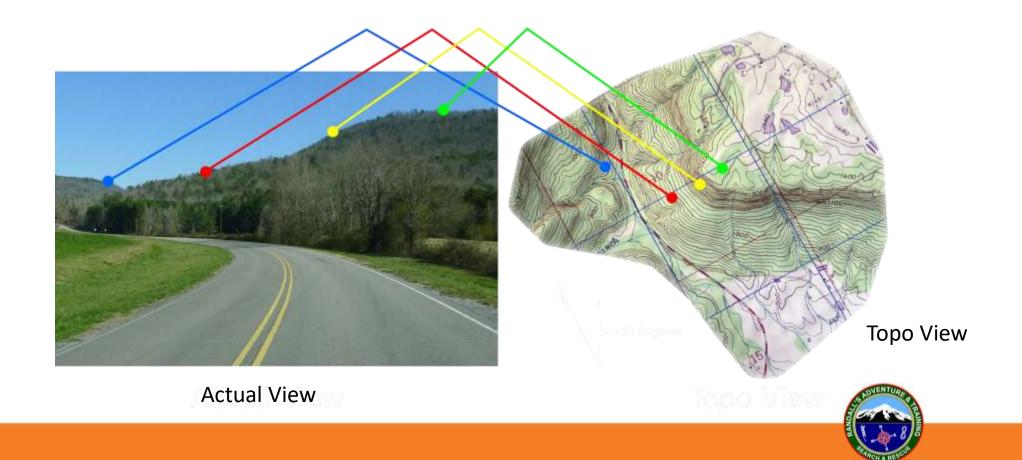






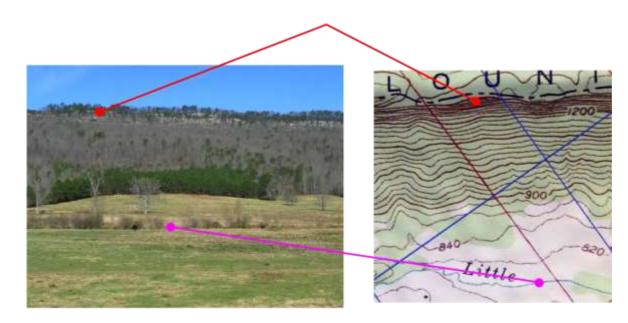


#### **Map Interpretation**

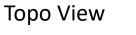




#### **Map Interpretation**



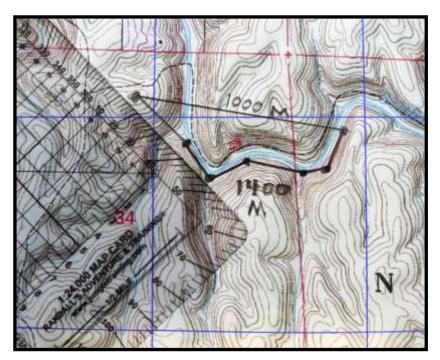
Actual View







#### **Determining Distance on a Map**



Use the correct scale card!







#### Pace Count (Tally)

(Not a preferred method for overall navigation. Use checkpoints instead.)

Pace counting in varying terrain is an estimate at best. To be accurate, the navigator must practice pacing over different types of terrain. It's best use is for blocking around an area or object, or for short distance calculations such as measuring from backstops.

Averages				
	Flat easy terrain	100 meters	65 paces	
	Rougher terrain with some slope	100 meters	75 paces	
	Steep hill terrain	100 meters	95 paces	

General Rule: You have never traveled as far as you think you have.





# **Pace Count Beads**

(Not a preferred method for overall navigation. Use checkpoints instead.)







### **Conditions That Affect Pace Count**

- Slopes Your pace lengthens on a downslope and shortens on an upgrade.
- Winds A headwind shortens the pace and a tailwind increases it.
- Surfaces Sand, gravel, mud, snow and similar surfaces tend to shorten your pace.
- Elements Falling rain or snow causes the pace to be reduced in length.
- Clothing Excess clothing or shoes with poor traction affect the pace length.
- Visibility Poor visibility due to rain, snow, or fog will shorten your pace.

Your pace (or tally) should be determined by walking a variety of courses with your pack on.

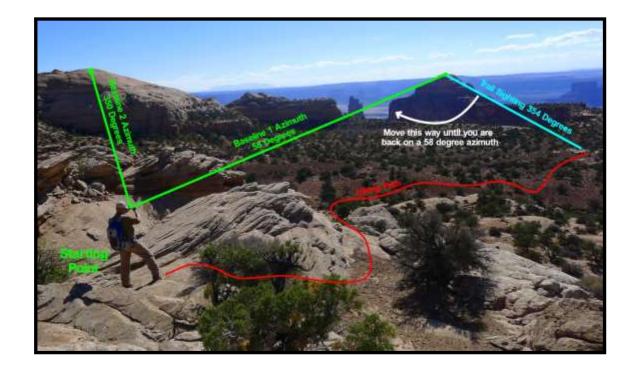




### **Baselines**

- Find two prominent features.
- Take an azimuth to the first one and write it down.
- Take an azimuth to the second one and write it down.
- If you get lost, take an azimuth to the first feature and move until you get back on your first azimuth line.
- Take an azimuth to your second feature and move until you get back on your second azimuth line.

Declination does not matter. All that is important is the ability to see your reference features.

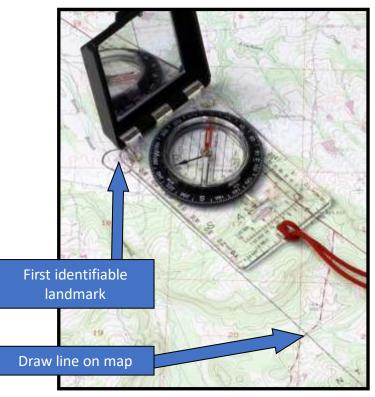






Resection Without Grid Lines

- Orient your map and secure its position.
- Locate a landmark on the map that you can actually see in the landscape.
- Take a compass bearing to that landmark by sighting and then rotating compass dial until the needle is boxed.
- Once you have a bearing, do not move the compass dial. Lay the corner of the compass on the map landmark and rotate the whole compass (not the dial) until the needle is boxed.
- If done properly the corner of the compass will still be over your landmark. Draw a line along the edge of the compass base.

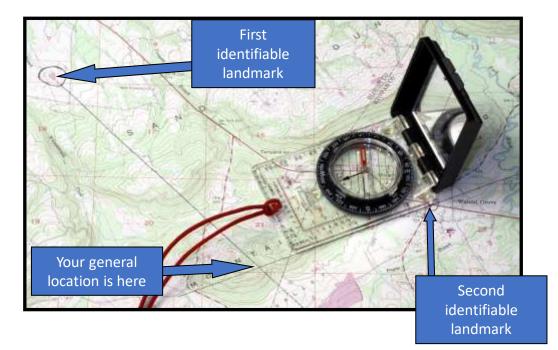






### **Resection – Step 2**

- Find a second identifiable landmark on the map and repeat the process from the previous slide.
- Where the two lines intersect is roughly where you are on the map.
- Finding a third point on the map and repeating the process is called "triangulation" and increases the accuracy of finding your location.







### **Resection / Intersection**

If you are already on a known location (such as a road, river or mountain ridge) but not sure exactly where you are on this feature, you may only need to shoot one azimuth to determine your exact position on the map.

INTERSECTION is the reverse of RESECTION. An example of intersection is seeing smoke from a forest fire and determining where the fire is located on a map.







### **Coordinate Systems**

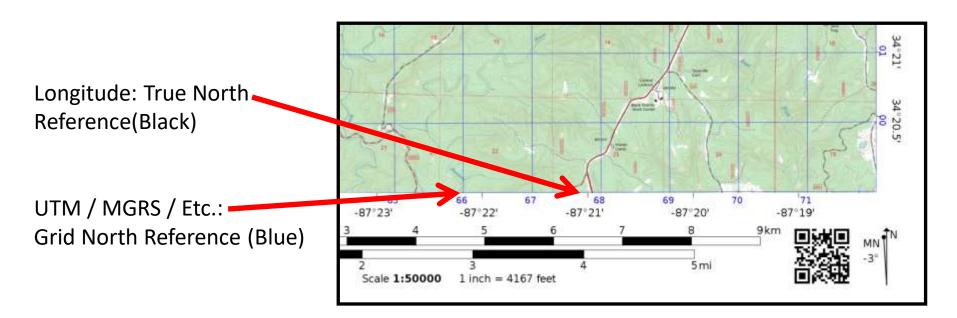








### Map Grids



When using a GPS with a map, set your GPS to the grid system you are using on the map.







# **Universal Transverse Mercator (UTM)**

- A rectangular coordinate system based on the latitude and longitude (geographic) coordinate system.
- The earth is divided into 60 zones that allows it to be projected onto maps with minimal distortion.
- All coordinates are expressed in meters.
- The UTM/USNG grid system is the easiest method of relaying your position to others, finding yourself
  on a map after getting a location fix with a GPS unit, or navigating to a position on a map using a GPS
  unit.

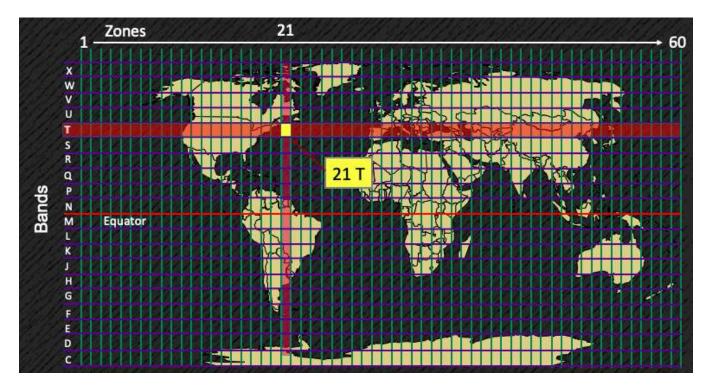






### **Universal Transverse Mercator (UTM)**

UTM Coordinate System is comprised of 60 Zones and 20 Latitude Bands

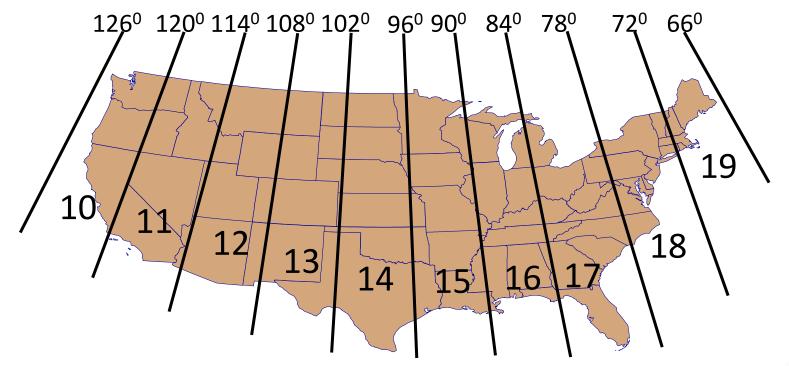








### **UTM Zones**



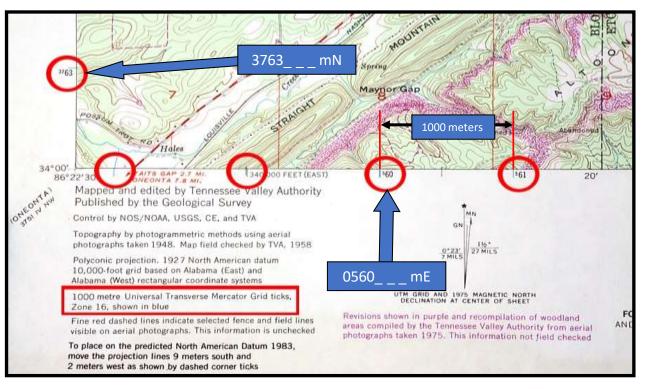






# UTM / USNG

1000 meter increments already printed on the map. The navigator only has to plot the distance between the 1000 meter increments.





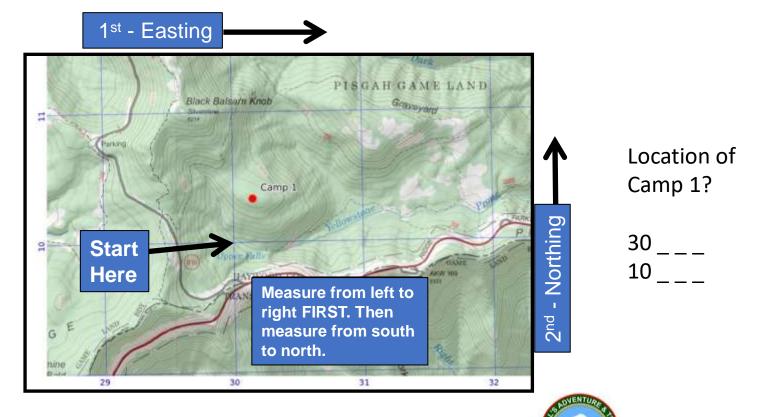


# **Determining Easting / Northing**

Easting: A designation of the EAST/WEST position in the grid. Read this direction first. Read from left to right.

Northing: a designation of how many meters you are north or south of the equator. Read this direction after reading easting. Read from south to north.

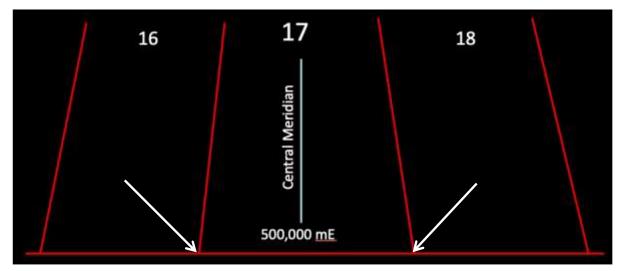
Always start your measurement in the southwest corner of the 1000 meter square grid your desired target is located.





# Easting

- Easting values are based on a Central Meridian of the zone.
- All Central Meridians are designated 500,000 meters east.
- At the Equator the widest zone is 674,000 meters. The zone would start at 163,000 meters on the left and end at 837,000 meters on the right.
- Due to working from a Central Meridian, there will be no "0" Easting values.







# Northing

The Northing values on the map are the number of meters north or south of the Equator.

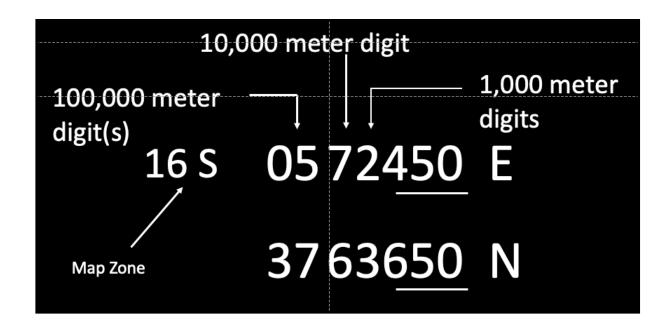
To avoid negative numbers, Northing values start at 10,000,000 M at the Equator (when going south) and count down.

North of the Equator, the numbers on the map are the actual number of meters above the Equator.





### **Plotting Coordinates**

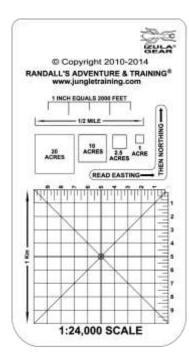


You only have to plot the last 3 numbers. The rest of the coordinate values are provided on the map.





### **Grid Readers**



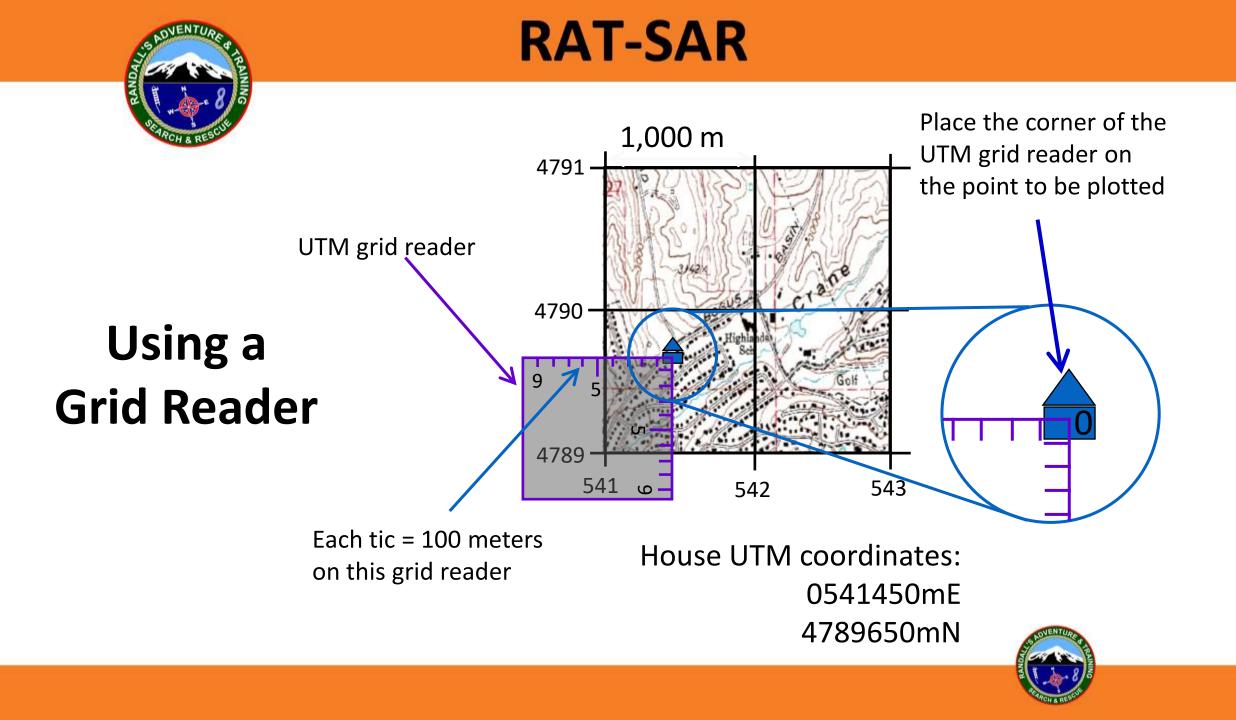
Verify scale matches map.

Read EASTING first.

Then read NORTHING.









# U.S. National Grid (USNG)

- Nationally consistent alpha-numeric georeferencing system.
- Uses a grid zone designation, a 100,000-meter square designation, and grid coordinates.
- Each 6-by-8-degree GZD (grid zone designator) is then covered by a specific scheme of 100,000-meter squares where a two-letter pair identifies each square.
- A point within the 100,000-meter square can further be defined using the UTM grid coordinates.

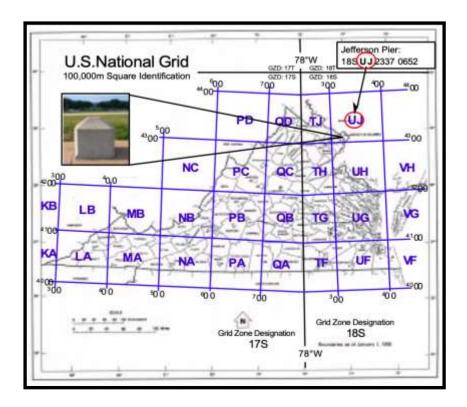
Difference between using USNG and UTM systems (differences shown in red):

USNG	UTM
16S DD 67713	16S <mark>04</mark> 67713
DD 01518	<mark>38</mark> 01518





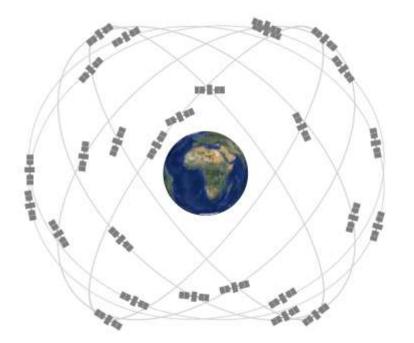
### U.S. National Grid (USNG)







### **GNSS / GPS Navigation**



A GNSS, or Global Navigation Satellite System, is a generic name for a group of artificial satellites that send position and timing data from their high orbits. The GPS, or Global Positioning System, is just one of the many different sets of satellites that can provide such data.

The satellites are arranged in geosynchronous orbits – Each one's speed and altitude is carefully controlled so that it stays in the same place in the sky.

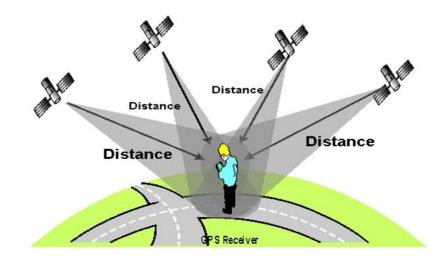




### How a GPS Works

GPS receivers are programmed to receive information about where each satellite is at any given moment. A GPS receiver determines its own location by measuring the time it takes for a signal to arrive at its location from at least four satellites.

Because radio waves travel at a constant speed, the receiver can use the time measurements to calculate its distance from each satellite.







### Pros / Cons of GPS

#### Pros:

- GPS units require little to no navigation training.
- GPS units automatically store waypoints and locations.
- GPS portrays your current location to your destination at all times.

#### Cons:

- GPS units rely on batteries and electronics.
- GPS units rely on the satellite system to always be working.
- GPS units may not work under heavy canopy or in deep canyons.
- GPS accuracy made be degraded in areas with spotty coverage.
- GPS is relied on too much for navigation; potentially affecting ability to navigate by other means.





### **Minimal User Knowledge**

- Turn unit on and off.
- Check battery charge / change batteries.
- Set map datum.
- Set units for distance.
- Set location data type, e.g., Lat/Long, UTM, etc.
- Clear track log, turn track log on, turn track log off.
- Set a waypoint.
- Use waypoint manager to get azimuth / distance.





### **Map Datum**

When using a GPS unit in conjunction with a map, it is imperative that the datum setting in the GPS match the datum the map is built on, e.g., WGS84, NAD27, etc.









### **GPS Setup**

GPS units vary on how to set them up, but the following items should be setup on any unit prior to use. Settings should match the format and datum being used.



Distance



**Position Format** 



Map Datum





### Using GPS With Map & Compass



#### Plotting GPS to Map

- 1) Find current location with GPS.
- 2) Use scale card to plot current location on the map.

#### Plotting Map to GPS

- 1) Plot location on map of where you want to go with a scale card.
- 2) Enter plotted coordinates into the GPS as a new waypoint.





### Using GPS

Any person using a GPS unit should have the ability to:

- State their location in any format specified.
- Recognize when the GPS receiver is not operating properly .
- Recognize that satellite coverage is adequate for recording usable data.
- Determine the current location.
- Obtain location information from a GPS receiver and correlate it to a topographic map.





### **Communicating Location**

If you are lost and can communicate with search personnel, try to give them the following info:

- General location (big picture)
- Type of navigation grid used
- Grid location (Easting Then Northing)
- Direction of travel if moving

#### Note:

A 4/4 (8-digit) grid will put you within 10 meters. It is communicated by dropping the last digit in a 5-digit grid and rounding up or down. For example, if your full 5-digit grid is 74356 / 63982, a 4/4 grid will be called out as 7436 / 6398.





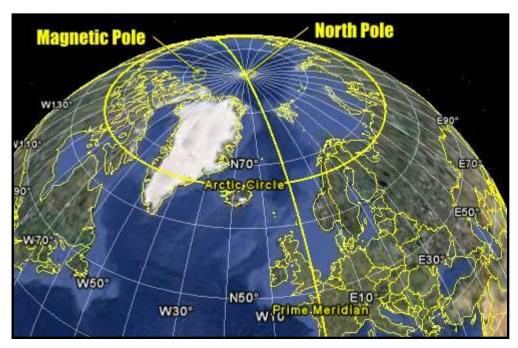
### Declination

- Magnetic Declination is the difference between True North (Longitude Line) and Magnetic North (where the compass needle points).
- A compass needle ALWAYS points to Magnetic North.
- Grid Declination is the difference between Grid North (Grid Reference Line) and Magnetic North (where the compass needle points).
- When going from map to the field, you will add westerly declination. When going from the field back to map you will subtract westerly declination.
- Easterly declination will be the opposite.

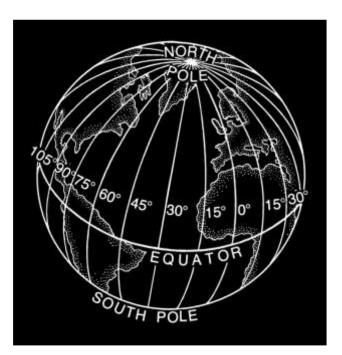




### **True North vs. Magnetic North**



Difference in True North and Magnetic North Magnetic North is moving approximately 35 miles per year.

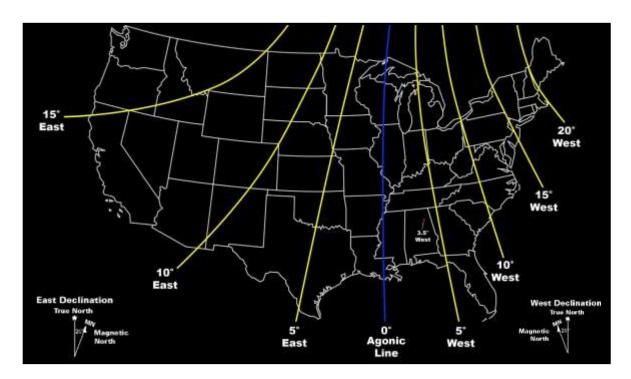


Longitude Lines (True North)



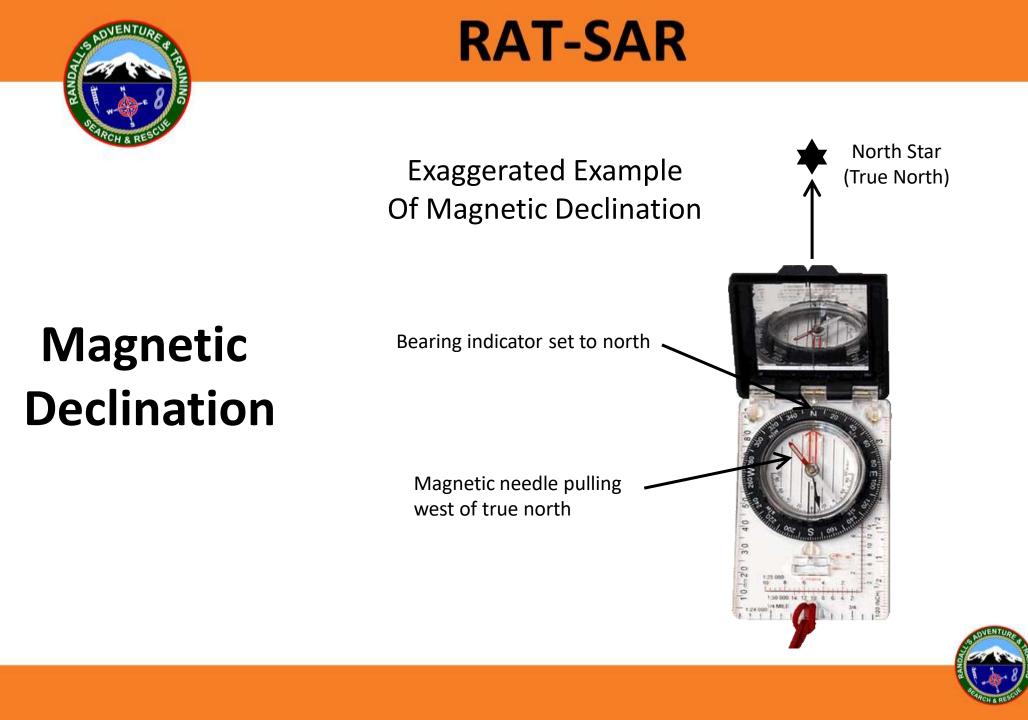


### **Magnetic Declination**



If you do not have a compass that adjusts for declination remember to add or subtract declination to your azimuth.







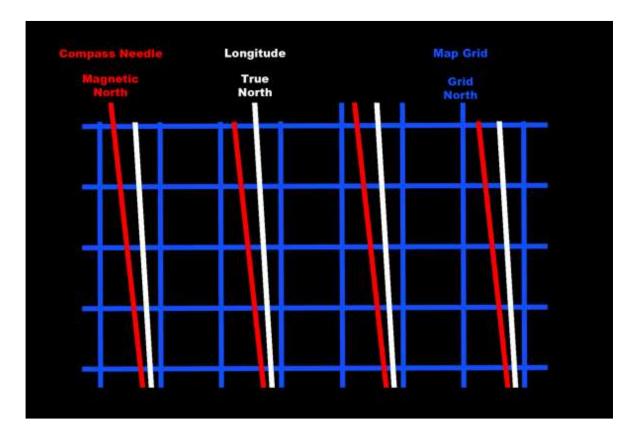
### **Magnetic Declination**

- Magnetic Declination is the difference between true north and magnetic north when using the longitude lines as north reference for measuring your bearing.
- Grid Declination is the difference between grid north and magnetic north when using the UTM grid lines as north reference.
- If the MN line is left of the reference line you are using to measure your azimuth, then it will be West Declination.
- If the MN line is right of the reference line it will be East Declination.
- If you are using a compass that is not adjusted for declination, add the amount for west declination when going from map to the field, subtract the amount for east declination (when going from map to field).
- When going from field back to map it will be opposite: Subtract for West and add for East.
- If your compass is adjustable for declination, set it for the north reference declination value you are using. No further addition or subtraction is required – set it and forget it.





### **Magnetic Declination**









### **Magnetic Declination**

GRID AZIMUTH: Measurement taken on the map using a grid line as a reference.

MAGNETIC AZIMUTH: Measurement taken in the field using the compass needle as the reference.

West Declination: Add when going from grid to magnetic. Subtract when going from magnetic to grid.

East Declination: Subtract when going from grid to magnetic. Add when going from magnetic to grid.





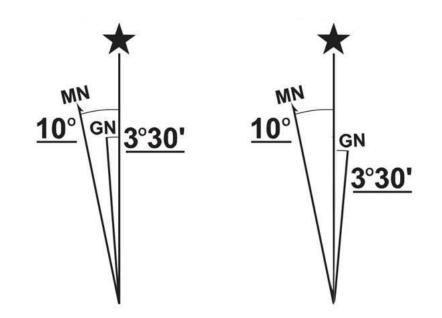
### **Magnetic Declination**

What is the declination value for each of the diagrams using Grid North Reference?

Degrees?

East or West?

If we want to walk a 30 degree grid azimuth in the field, what would we set the compass on?







### Land Nav Checklist

- Verify Coordinates
  - Pace / Distance
- Azimuth / Declination
- Checkpoint / Terrain Association
  - Backstops, Handrails, etc.

Write it all down!







# **Questions?**

